A Decision Theoretic Approach to Modeling Multiple Bounded Uncertainty Choice Data[1]

Proposed running title

Address correspondence to

Abstract

1. Introduction

e.g.

2. Review of Prior Findings: Respondent uncertainty and the multiple bounded uncertainty choice format

V_i $F \cdot$

$$V_i = x_i! + \varepsilon_i \quad x_i$$

$$\varepsilon_i$$

$$F \cdot \qquad\qquad\qquad\qquad\qquad\qquad\qquad\qquad \varepsilon_i$$

$G_i \bullet$ i i

b

$P_i V_i \quad b = - G_i b \quad V_i \quad i$

$Pr\ event\ occurs =$ $Pr\ event\ occurs =$

i $b\ V_i \quad b$

$b\ P_i V_i \quad b = - G_i b =$

individual

4.1 An optimal decision rule for continuous uncertainty responses

(1) $$R_i\, b = P_i\, V_i \quad b = -P_i\, V_i \quad b = -G_i\, b$$

V_i !

L ! v_i i

(2) *Average loss of* # = E_i l L ! v_i #

(3) l L ! v_i # = L ! v_i − #

(4) = E_i (L ! V_i − #)
#

(5) #* = E_i L ! v_i

(6)

$$\#^{*} = E_i \; L \; ! \; V_i \quad = \int_{-\infty}^{\infty} L \; ! \; v \; dP_i \, v$$

$$R_i \, b_k = P_i \, V_i \quad b_k = - P_i \, V_i \quad b$$

(8) $\$ = \{ -\infty \quad b \quad b \quad b \quad b_{K-} \quad b_K \quad b_K \quad \infty \}$

$= \{$

$$\#^{*} = E_i \quad L \; ! \quad V_i \qquad = P_i \, V_i \qquad b \quad \cdot \qquad F$$

(11) $WTP_i = \% + \&_i$

$\&_i$ '

WTP_i % '

i.e.

6. Conclusions

References

J. Environ. Econom. Management

J. Environ. Econom. Management

Journal of Forecasting **1**

J. Environ. Econom. Management

Rev. Econ. and Statist. **80**

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Bulletin of the Psychonomic Society **31(2)**

J. Environ. Econom. Management **32**

J. Environ. Econom. Management **36**

Environmental and Resource Economics **11**

Figure 1: Multiple Bounded Uncertainty Choice Sample Response

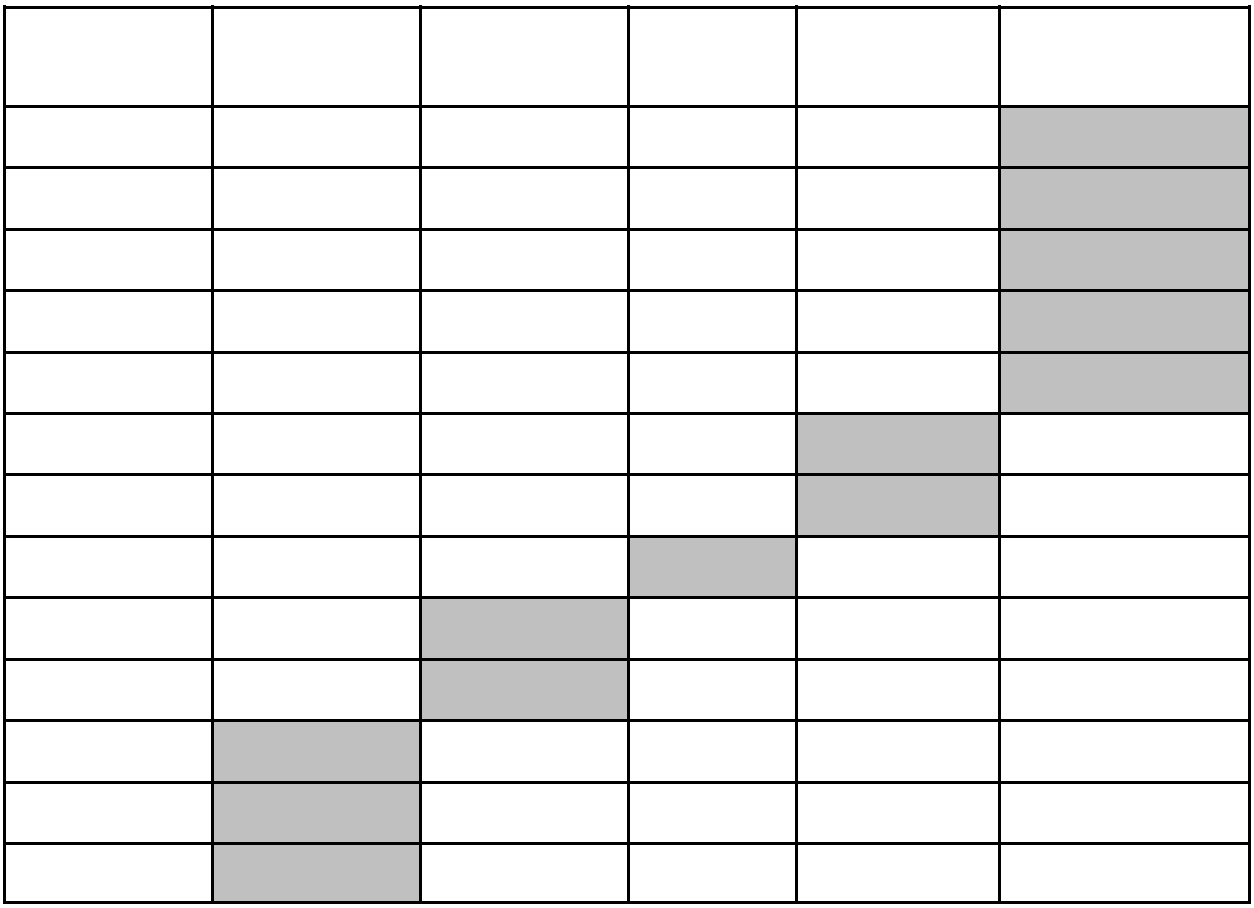

Table II: Estimation Results for Maine Moose Hunting Study[1]

	Definitely Yes Model	Probably Yes Model	Not Sure Model	Benchmark Decision Theory Model

Table III: Estimation Results for Maine Moose Hunting Study–Sensitivity of decision theory estimates to assignment of probabilities[1]

	Symmetric Assignments		Asymmetric Assignments	
	1, 0.99, 0.5, 0.01, 0	**1, 0.6, 0.5, 0.4, 0**	**Benchmark[2]: 1, 0.75, 0.5, 0.15, 0**	**1, 0.99, 0.98, 0.5, 0**

Table IV: Estimation Results for Glen Canyon Pilot Study[1]

	Definitely Yes Model	Probably Yes Model	Not Sure Model	Benchmark Decision Theory Model
Version 1				
Version 2				
Version 3